## Limiting Values under Scaling of the Lebesgue Function for Polynomial Interpolation on Spheres

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We consider interpolation by spherical harmonics at points on a (d-1)-dimensional sphere and show that, in the limit, as the points coalesce under an angular scaling, the Lebesgue function of the process converges to that of an associated algebraic interpolation problem for the original angles considered as points in  $\mathbb{R}^{d-1}$ . © 1999 Academic Press

Univariate polynomial interpolation is a classical and much studied subject with many beautiful theoretical results as well as being of some practical importance. In contrast, the multivariate case has been much less studied and many basic questions remain open. A special case of particular interest is interpolation on the sphere and it is the purpose of this work to study one basic property of such interpolants: what happens in the limit as the points coalesce to a single point under an angular scaling? Somewhat unexpectedly the answer (see our main theorem) is that the interpolation problem becomes one on a certain paraboloid!

In order to explain the details we begin with a general setup for polynomial interpolation in several variables. Let  $K \subset \mathbb{R}^d$  be compact. The polynomials of degree *n*, when restricted to *K*, form a certain vector space which we will denote by  $\mathcal{P}_n(K)$ . Let  $d_n := \dim(\mathcal{P}_n(K))$  and let  $\{P_1, ..., P_{d_n}\}$  be a basis for  $\mathcal{P}_n(K)$ . Suppose that we are given a set  $X = \{x_1, ..., x_{d_n}\} \subset K$  of  $d_n$ 



distinct points and a function  $f \in C(K)$ . The polynomial interpolation problem is then to find  $P \in \mathcal{P}_n(K)$  such that

$$P(x_i) = f(x_i), \qquad 1 \le j \le d_n.$$

If *P* is written in the form

$$P = \sum_{k=1}^{d_n} c_k P_k,$$

this amounts to solving the  $d_n \times d_n$  linear system of equations

$$\sum_{k=1}^{d_n} c_k P_k(x_j) = f(x_j) \qquad 1 \leqslant j \leqslant d_n,$$

which has a unique solution iff the associated Vandermonde matrix

$$V(x_1, ..., x_{d_n}) := [P_k(x_j)]_{1 \le j, k \le d_n}$$

is non-singular. If this is indeed the case we may then form the fundamental Lagrange polynomials

$$l_k(x) := \frac{\det V(x_1, ..., x_{k-1}, x, x_{k+1}, ..., x_{d_n})}{\det V(x_1, ..., x_{d_n})}$$
(1)

having the property that

$$l_k(x_j) = \delta_{jk} \qquad 1 \le j, k \le d_n$$

This allows the interpolant to be written in the form

$$P(x) = \sum_{k=1}^{d_n} f(x_k) \, l_k(x).$$

The function

$$\Lambda_n(x) := \sum_{k=1}^{d_n} |l_k(x)|$$

is known as the Lebesgue function of the process. Its maximum value,  $\lambda_n := \max_{x \in K} \Lambda_n(x)$ , is referred to as the associated Lebesgue constant and gives the norm of the interpolation projection,  $\pi_n: C(K) \to \mathcal{P}_n(K), f \to P$ , where both spaces are equipped with the supremum norm on K. It is fundamental to the study of the convergence of interpolants (see, e.g., [C] or [SV]). Now, as is well known, polynomial interpolation is well behaved under affine scalings. Specifically, for a scaling factor a > 0, if we let  $\tilde{K} := aK$ , let  $\tilde{X} := aX$ , and let  $l_k$  be the corresponding Lagrange polynomials, then

$$\hat{l}_k(ax_j) = \delta_{jk} = l_k(x_j)$$

so that, in fact,

$$\tilde{l}_k(ax) = l_k(x) \qquad (\text{in } \mathcal{P}_n(K)) \tag{2}$$

and hence

$$\tilde{\Lambda}_n(ax) = \Lambda_n(x).$$

In particular,

$$\widetilde{\lambda}_n := \max_{y \in \widetilde{K}} \widetilde{\Lambda}_n(y) = \max_{x \in K} \widetilde{\Lambda}_n(ax) = \max_{x \in K} \Lambda_n(x) = \lambda_n.$$

It follows that the Lebesgue constants are in fact *invariant* under affine scalings.

However, such affine scalings are not always what is required in practice. Consider, for example, interpolation of circular data by trigonometric polynomials. In our setting this corresponds to  $K = S^1$ , the unit circle,  $d_n = 2n + 1$ , and

$$X = \{(\cos(\theta_1), \sin(\theta_1)), ..., (\cos(\theta_{2n+1}), \sin(\theta_{2n+1}))\}.$$

The scaling appropriate to such a situation is angular, i.e.,

$$\tilde{X} = \{(\cos(a\theta_1), \sin(a\theta_1)), ..., (\cos(a\theta_{2n+1}), \sin(a\theta_{2n+1}))\}$$

But now there is a major difference. A trigonometric polynomial  $t(\theta)$  scaled to  $t(a\theta)$  is no longer in general even another trigonometric polynomial and thus a formula such as (2) will not be true. Nevertheless, as we shall see, there is a limiting value for each  $\tilde{l}_k(a\theta)$  as  $a \to 0$  and thus also for  $\tilde{\lambda}_n$ .

Surprisingly, these limiting values are the corresponding entities in an associated *algebraic* interpolation problem, dependent only on the initial values X. The argument is quite simple, provided a careful choice of basis is made. It goes as follows. Any bivariate polynomial P(x, y) of degree  $\leq n$  may be written in the form

$$P(x, y) = \sum_{k=0}^{n} a_k(x) y^k,$$
(3)

clearly

where  $a_k(x)$  is a polynomial of degree n-k. On the unit circle,  $x^2 + y^2 = 1$  or  $y^2 = 1 - x^2$ , and the substitution of this relation into (3) yields

$$P(x, y) = p_1(x) + yp_2(x)$$

for certain polynomials  $p_1$ ,  $p_2$  of degrees n and n-1, respectively. Hence, the monomials

$$\left\{x^k \mid 0 \leqslant k \leqslant n\right\} \cup \left\{yx^k \mid 0 \leqslant k \leqslant n-1\right\}$$

form a basis for  $\mathscr{P}_n(K)$ . However, for our purposes, it is more convenient to use the basis

$$\{(x-1)^k \mid 0 \le k \le n\} \cup \{y(x-1)^k \mid 0 \le k \le n-1\}.$$
 (4)

Now, on the circle, consider a typical point, scaled by an angular factor of a,  $(x, y) = (\cos(a\theta), \sin(a\theta))$ . Its coordinates have power series expansions

$$x = \cos(a\theta) = 1 - \frac{a^2\theta^2}{2!} + \frac{a^4\theta^4}{4!} + \cdots$$
$$y = \sin(a\theta) = a\theta - \frac{a^3\theta^3}{3!} + \cdots$$

so that

$$(x-1)^{k} = \left(-\frac{a^{2}\theta^{2}}{2!} + \frac{a^{4}\theta^{4}}{4!} - \cdots\right)^{k}$$
$$= a^{2k} \left(-\frac{\theta^{2}}{2!} + \frac{a^{2}\theta^{4}}{4!} - \frac{a^{4}\theta^{6}}{6!} + \cdots\right)^{k}$$
$$= a^{2k} \left(\frac{(-1)^{k}}{(2!)^{k}} \theta^{2k} + a^{2}R_{k}(\theta, a)\right),$$
(5)

for some analytic function  $R_k(\theta, a)$  whose precise form is unimportant. Similarly,

$$(x-1)^{k} y = a^{2k+1} \left( \frac{(-1)^{k}}{(2!)^{k}} \theta^{2k+1} + a^{2} Q_{k}(\theta, a) \right),$$
(6)

again for some analytic function  $Q_k(\theta, a)$ .

Hence, when computing  $l_j(a\theta)$  by means of the expression (1), we see that the column corresponding to the basis function  $(x-1)^k$  has a common factor of  $a^{2k}$  and that corresponding to  $(x-1)^k y$  one of  $a^{2k+1}$ . Since this holds for both numerator and denominator, these powers of a simply

cancel out. Thus, letting  $a \to 0$ , we see from (5) and (6) that the column corresponding to  $(x-1)^k$  tends to  $(-1)^k \theta^{2k}/(2!)^k$  and that to  $(x-1)^k y$  tends to  $(-1)^k \theta^{2k+1}/(2!)^k$ . The factors  $(-1)^k/(2!)^k$  are entirely irrelevant and we therefore may conclude that, as  $a \to 0$ ,  $l_j(a\theta)$  tends to the corresponding Lagrange polynomial for the algebraic interpolation problem associated with the basis

$$\{\theta^{2k} \mid 0 \leqslant k \leqslant n\} \cup \{\theta^{2k+1} \mid 0 \leqslant k \leqslant n-1\} = \{\theta^k \mid 0 \leqslant k \leqslant 2n\}$$

and the points  $\theta_1, \theta_2, ..., \theta_{2n+1} \in \mathbb{R}$ .

An analogous result holds for higher dimensional spheres. Thus, let  $K = S^{d-1} \subset \mathbb{R}^d$ ,

the unit sphere. As is well known,

$$d_n = \binom{n+d-1}{n} + \binom{n+d-2}{n-1}.$$

Now let  $x \in \mathbb{R}^{d-1}$  and  $y \in \mathbb{R}$  so that  $(x, y) \in \mathbb{R}^d$ . Then just as in (3), any *d*-variate polynomial P(x, y) of degree  $\leq n$  may be written in the form

$$P(x, y) = \sum_{k=0}^{n} a_k(x) y^k,$$

where  $a_k(x)$  is a (d-1)-variate polynomial of degree at most n-k. On  $S^{d-1}$ ,  $y^2 = 1 - |x|^2$  so that

$$P(x, y) = p_1(x) + yp_2(x)$$

for certain polynomials  $p_1$ ,  $p_2$  of degree at most n and n-1 respectively.

Consequently, the monomials

$$\{x^{\alpha}: |\alpha| \leq n\} \cup \{yx^{\beta}: |\beta| \leq n-1\}$$

form a basis for  $\mathscr{P}_n(S^{d-1})$  but, as before, it is more convenient to use the basis

$$\{(x-e_1)^{\alpha}: |\alpha| \leq n\} \cup \{y(x-e_1)^{\beta}: |\beta| \leq n-1\},\$$

where  $e_1 := (1, 0, ..., 0) \in \mathbb{R}^{d-1}$ .

Suppose then that we are given  $d_n$  distinct points  $(x^k, y^k) \in S^{d-1}$ ,  $1 \le k \le d_n$ . We will write each such point in slightly non-standard spherical coordinates,

$$\begin{aligned} x_{2}^{k} &= \cos(\theta_{1}^{k})\sin(\theta_{2}^{k}) \\ x_{3}^{k} &= \cos(\theta_{1}^{k})\cos(\theta_{2}^{k})\sin(\theta_{3}^{k}) \\ \vdots \\ x_{d-1}^{k} &= \cos(\theta_{1}^{k})\cos(\theta_{2}^{k})\cdots\cos(\theta_{d-2}^{k})\sin(\theta_{d-1}^{k}) \\ x_{1}^{k} &= \cos(\theta_{1}^{k})\cos(\theta_{2}^{k})\cdots\cos(\theta_{d-2}^{k})\cos(\theta_{d-1}^{k}) \\ y^{k} &= \sin(\theta_{1}^{k}), \end{aligned}$$

$$(7)$$

and then scale the angles  $\theta_j$  by the factor *a*. Thus, the points coalesce at (1, 0, ..., 0) as  $a \to 0$ . (Note: This choice is made so that each coordinate has *one* sin factor, which ensures that they converge at the same rate. Other choices of coordinates may not scale all of them in a uniform manner, which will have a pronounced affect on the limit. See the example below.) We calculate, much as before (suppressing the superscript),

$$\begin{aligned} x_{2} &= \cos(a\theta_{1})\sin(a\theta_{2}) \\ &= \left(1 - \frac{a^{2}\theta_{1}^{2}}{2!} + \frac{a^{4}\theta_{1}^{4}}{4!} + \cdots\right) \left(a\theta_{2} - \frac{a^{3}\theta^{3}}{3!} + \cdots\right) \\ &= a\theta_{2} + a^{3}R_{2}(a, \theta_{1}, \theta_{2}) \\ &= a\{\theta_{2} + a^{2}r_{2}(a, \theta_{1}, \theta_{2})\} \\ x_{3} &= \cos(a\theta_{1})\cos(a\theta_{2})\sin(a\theta_{3}) \\ &= \left(1 - \frac{a^{2}\theta_{1}^{2}}{2!} + \cdots\right) \left(1 - \frac{a^{2}\theta_{2}^{2}}{2!} + \cdots\right) \left(a\theta_{3} - \frac{a^{3}\theta_{3}^{3}}{3!} + \cdots\right) \\ &= a\theta_{3} + a^{3}R_{3}(a, \theta_{1}, \theta_{2}, \theta_{3}) \\ &= \{\theta_{3} + a^{2}R_{3}(a, \theta_{1}, \theta_{2}, \theta_{3})\} \\ \text{etc.} \end{aligned}$$

In general, we have

$$x_k = a\theta_k + a^2 R_k(a, \theta_1, ..., \theta_k), \qquad 2 \leq k \leq d-1.$$

The first coordinate is somewhat different:

$$x_{1} - 1 = \cos(a\theta_{1})\cos(a\theta_{2})\cdots\cos(a\theta_{d-1}) - 1$$
  
=  $\left(1 - \frac{a^{2}\theta_{1}^{2}}{2!} + \cdots\right)\cdots\left(1 - \frac{a^{2}\theta_{d-1}^{2}}{2!} + \cdots\right) - 1$   
=  $a^{2}\left\{\frac{-1}{2!}(\theta_{1}^{2} + \cdots + \theta_{d-1}^{2}) + a^{2}R_{1}(a, \theta_{1}, ..., \theta_{d-1})\right\}.$ 

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$$y = \sin(a\theta_1)$$
$$= a\{\theta_1 + a^2 R_d(a, \theta_1)\}.$$

The precise forms of the analytic functions  $R_1, ..., R_d$  are unimportant.

Again, when these expressions are substituted into (1), we find that the common powers of *a* cancel, and thus in the limit, as  $a \rightarrow 0$ , we replace

$$(x-e_1)^{\alpha}$$
 by  $(\theta_1^2+\cdots+\theta_{d-1}^2)^{\alpha_1}\theta_2^{\alpha_2}\cdots\theta_{d-1}^{\alpha_{d-1}}$ 

and

$$y(x-e_1)^{\beta}$$
 by  $(\theta_1^2 + \dots + \theta_{d-1}^2)^{\beta_1} \theta_1 \theta_2^{\beta_2} \dots \theta_{d-1}^{\beta_{d-1}}$ .

Clearly then, in the limit, we obtain the problem of interpolation at the  $d_n$  points

$$\{\theta^k \mid 1 \leqslant k \leqslant d_n\} \subset \mathbb{R}^{d-1}$$

by polynomials of the form

$$p_1(\theta_2, ..., \theta_d) + \theta_1 p_2(\theta_2, ..., \theta_d), \tag{8}$$

where deg  $(p_1) \leq n$ , deg  $(p_2) \leq n-1$ , and  $\theta_d = \theta_1^2 + \theta_2^2 + \cdots + \theta_{d-1}^2$ . Let  $A_n$  denote the space of such polynomials; i.e.,

$$A_n := \{ p_1(\theta_2, ..., \theta_d) + \theta_1 p_2(\theta_2, ..., \theta_d) \mid \deg(p_1) \leq n, \\ \deg(p_2) \leq n - 1, \ \theta_d = \theta_1^2 + \dots + \theta_{d-1}^2 \}.$$

Since  $p_1$ ,  $p_2$  are polynomials in d-1 variables, it follows that

$$\begin{split} \dim(A_n) &\leqslant \dim(\mathscr{P}_n(\mathbb{R}^{d-1})) + \dim(\mathscr{P}_{n-1}(\mathbb{R}^{d-1})) \\ &= \binom{n+d-1}{n} + \binom{n-1+d-1}{n-1} \\ &= d_n. \end{split}$$

We claim that, in fact,  $\dim(A_n) = d_n$  and hence this interpolation problem is well posed. To show this, it suffices to show that

$$p_{1}(\theta_{2}, ..., \theta_{d-1}, \theta_{1}^{2} + \dots + \theta_{d-1}^{2}) + \theta_{1} p_{2}(\theta_{2}, ..., \theta_{d-1}, \theta_{1}^{2} + \dots + \theta_{d-1}^{2}) \equiv 0$$
(9)

for all  $\theta_1, ..., \theta_{d-1} \in \mathbb{R}$  iff  $p_1 \equiv 0$  and  $p_2 \equiv 0$ . So suppose that (9) holds. Since this is an algebraic identity it also holds for all  $\theta_1, ..., \theta_{d-1} \in \mathbb{C}$ . In particular, it holds for  $\theta_1 = it(\theta_2^2 + \cdots + \theta_{d_1}^2)^{1/2}$ ,  $t \in \mathbb{R}$ , for which  $\theta_1^2 + \cdots + \theta_{d-1}^2 = (1-t^2)(\theta_2^2 + \cdots + \theta_{d_1}^2)$ . Hence,

$$p_1(\theta_2, ..., \theta_{d-1}, (1-t^2)(\theta_2^2 + \dots + \theta_{d-1}^2)) + it(\theta_2^2 + \dots + \theta_{d-1}^2)^{1/2} p_2(\theta_2, ..., \theta_{d-1}, (1-t^2)(\theta_2^2 + \dots + \theta_{d-1}^2)) \equiv 0.$$

Equating real and imaginary parts, we have

$$p_1(\theta_1, ..., \theta_{d-1}, (1-t^2)(\theta_2^2 + \cdots + \theta_{d-1}^2)) \equiv 0$$

and

$$p_2(\theta_2, ..., \theta_{d-1}, (1-t^2)(\theta_2^2 + \cdots + \theta_{d-1}^2)) \equiv 0.$$

But since  $t \in \mathbb{R}$  is arbitrary it follows that  $p_1 \equiv 0$  and  $p_2 \equiv 0$ , as claimed.

There is an interesting geometric interpretation of the space  $A_n$ . By definition it consists of polynomials of the special form (8), restricted to the *paraboloid*  $\theta_d = \theta_1^2 + \cdots + \theta_{d-1}^2$ . But the dimension of the space of *all* polynomials in  $\theta_1, ..., \theta_d$ , restricted to this paraboloid is also  $d_n$  (for the same reason as for the sphere). Hence, letting

$$Q^{d-1} := \{ (\theta_1, ..., \theta_d) | \theta_d = \theta_1^2 + \cdots + \theta_{d-1}^2 \} \subset \mathbb{R}^d$$

be this paraboloid, we have

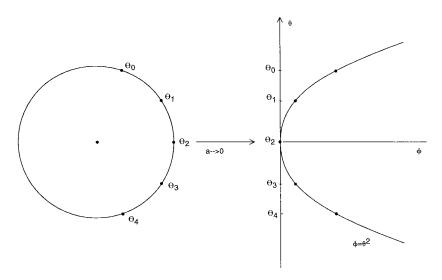
$$A_n = \mathscr{P}_n(Q^{d-1}).$$

In summary, we have established the following theorem giving the "*limiting value under scaling*" for polynomial interpolation on spheres

THEOREM. Suppose we are given  $d_n$  distinct points on the sphere,  $(x^k, y^k) \in S^{d-1}, 1 \leq k \leq d_n$ . Consider two interpolation problems associated to these points:

(1) Spherical interpolation. Interpolate a function  $f \in C(S^{d-1})$  at the points  $(x^k, y^k)$  by a polynomial  $p \in \mathcal{P}_n(S^{d-1})$ . Denote the fundamental Lagrange polynomials by  $l_k(x)$ .

(2) Paraboloidal interpolation. First write the points in spherical coordinates as in (7). Interpolate a function  $g \in C(Q^{d-1})$  at the  $d_n$  points  $(\theta^k, \theta^k_d) \in Q^{d-1}$  with  $\theta_d = \theta_1^2 + \cdots + \theta_{d-1}^2$  by a polynomial  $p \in \mathcal{P}_n(Q^{d-1})$ . Denote the fundamental Lagrange polynomials by  $\tilde{l}_k(\theta)$  (if they exist, i.e. the problem is unisolvent).





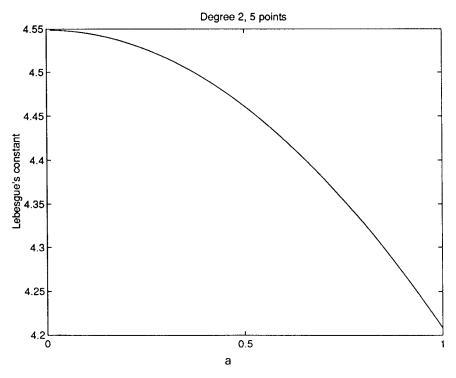


FIG. 2. The behavior of the Lebesgue function for five equally spaced points.

Let us denote by x(a) the point obtained by scaling the angles in (7) by the factor a and by  $l_k^a$  the fundamental Lagrange polynomial associated to all the given points on the sphere scaled by a in this manner. Then

$$\lim_{a \to 0} l_k^a(x(a)) = \tilde{l}_k(\theta).$$

The geometry underlying the theorem is illustrated in Fig. 1 for the case d=2.

COROLLARY. Suppose that K is a compact subset of  $S^{d-1}$  and that the set of points  $X \subset K$ . As before, let  $\lambda_n := \max_{x \in K} \Lambda_n(x)$  denote the associated Lebesgue constant. Further, let  $\tilde{K}$  and  $\tilde{X}$  denote the angular scalings of these sets by means of the spherical coordinates (7), and let  $\tilde{\lambda}_n$  be the corresponding Lebesgue constant. Then, if we let  $K_{\theta}$  be the image of K under the inverse of the mapping  $\theta \to x$  given by (7), the limit of  $\tilde{\lambda}_n$  as  $a \to 0$  is the Lebesgue constant associated to problem (2) in the theorem on the set  $K_{\theta}$ .

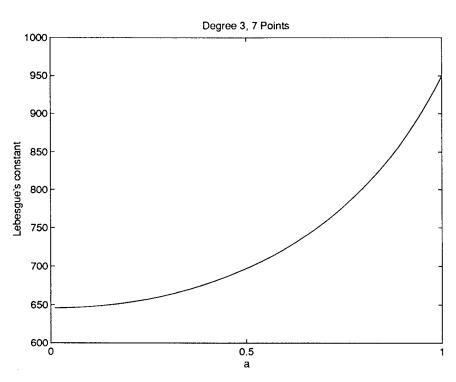


FIG. 3. The behavior of the Lebesgue function for seven points chosen at random.

In general, the limiting values of the Lagrange polynomials depend strongly on how the points coalesce. We give a simple example illustrating this fact.

EXAMPLE. Consider linear interpolation at four points on the sphere  $S^2$ . The spherical coordinates (7) specialize to

 $z = \sin(\phi)$  $x = \cos(\phi)\cos(\theta)$  $y = \cos(\phi)\sin(\theta)$ 

and the limit of the scaled interpolation problem corresponds to interpolation at the points  $(\theta, \phi)$  by a polynomial in the linear span of  $\{1, \theta, \phi, \theta^2 + \phi^2\}$ .

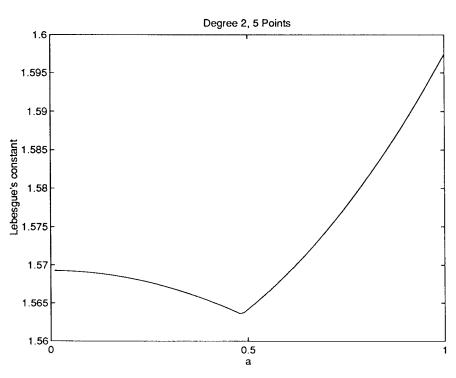


FIG. 4. The behavior of the Lebesgue function for five Chebyshev points.

If, on the other hand, we were to use the more standard spherical coordinates

$$z = \cos(\phi)$$
  

$$x = \sin(\phi) \cos(\theta)$$
  

$$y = \sin(\phi) \sin(\theta)$$

the limit would correspond to interpolation from the linear span of  $\{1, \phi, \theta\phi, \phi^2\}$ , as is easily seen from the Taylor expansions of the coordinate functions.

We conclude with several numerical examples illustrating the convergence for points on the circle. Figure 2 is of five equally spaced points on  $-\pi/4 \le \theta \le \pi/4$  and Fig. 3 is of seven points chosen at random. Although the convergence is monotone in both cases, Fig. 4 shows that this is not *always* true.

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